

Solving the Inverse Stellar Structure Problem

Lee Lindblom

Theoretical Astrophysics, Caltech

Institute of Theoretical Science Seminar
University of Oregon, 30 April 2013

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- Can the equation of state of the matter in a neutron star be determined from astronomical observations?
- This talk describes recent work on the mathematical, rather than observational or data analysis, aspects of this question.
 - What is the relativistic inverse stellar structure problem?
 - How can it be solved?
 - How well does the solution work in practice?
 - Can gravitational wave data be used to solve this problem?

Relativistic Stellar Structure Problem (SSP)

- Given an equation of state, $\epsilon = \epsilon(\rho)$, solve Einstein's equations,

$$\frac{dm}{dr} = 4\pi r^2 \epsilon,$$

$$\frac{dp}{dr} = -(\epsilon + \rho) \frac{m + 4\pi r^3 \rho}{r(r - 2m)},$$

to determine the structures of relativistic stars.

- Find the radius $\rho(R) = 0$ and mass $M = m(R)$ for each star.

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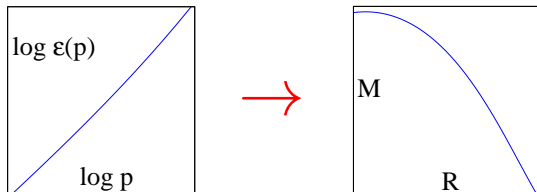
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to determine the structures of relativistic stars.

- Find the radius $\rho(R) = 0$ and mass $M = m(R)$ for each star.
- SSP can be thought of as a map from the equation of state $\epsilon = \epsilon(\rho)$ to the M-R curve $\{R(\rho_c), M(\rho_c)\}$.

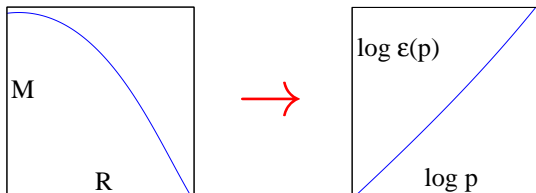


Relativistic Inverse Stellar Structure Problem (SSP⁻¹)

- When the equation of state is well understood – as in white dwarf stars – the standard stellar structure problem is useful.
- When the equation of state is poorly known – as in neutron stars – the inverse stellar structure problem (SSP⁻¹) is more interesting.

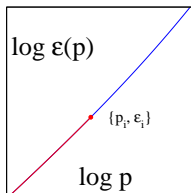
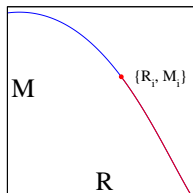
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- When the equation of state is well understood – as in white dwarf stars – the standard stellar structure problem is useful.
- When the equation of state is poorly known – as in neutron stars – the inverse stellar structure problem (SSP⁻¹) is more interesting.
- SSP⁻¹ finds the equation of state $\epsilon = \epsilon(p)$ from a given mass-radius curve.
- SSP⁻¹ can be thought of as the map from the M-R curve $\{R(p_c), M(p_c)\}$ to the equation of state $\epsilon = \epsilon(p)$.



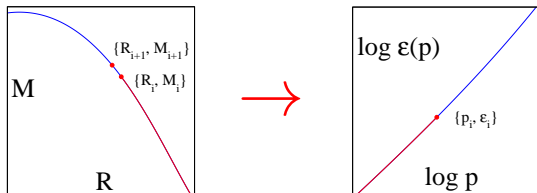
Standard Solution to SSP⁻¹

- Assume the complete M-R curve is known, including the point $\{R_i, M_i\} = \{R(p_i), M(p_i)\}$.
- Assume the equation of state is known for $\epsilon \leq \epsilon_i = \epsilon(p_i)$.



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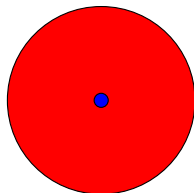
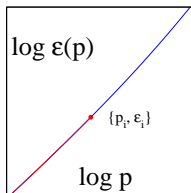
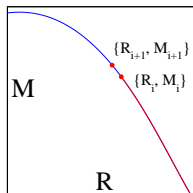
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- Choose a new point on the M-R curve, $\{R_{i+1}, M_{i+1}\}$, having slightly larger central density.
- Integrate Einstein's equations,

$$\frac{dm}{dr} = 4\pi r^2 \epsilon, \quad \frac{dp}{dr} = -(\epsilon + p) \frac{m + 4\pi r^3 p}{r(r - 2m)},$$

through the outer parts of the star, to determine the mass and radius, $\{r_{i+1}, m_{i+1}\}$, of the small core with large densities $\epsilon \geq \epsilon_i$.

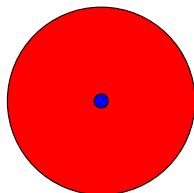
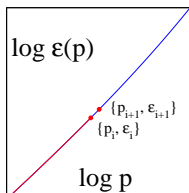
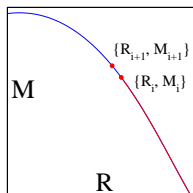
Standard Solution to SSP⁻¹ II

- For very small cores, $\{r_{i+1}, m_{i+1}\}$, the solution to the OV equations is described by the power series solution:

$$m_{i+1} = \frac{4\pi}{3} \epsilon_{i+1} r_{i+1}^3 + \mathcal{O}(r_{i+1}^5),$$

$$p_i = p_{i+1} - \frac{2\pi}{3} (\epsilon_{i+1} + p_{i+1})(\epsilon_{i+1} + 3p_{i+1}) r_{i+1}^2 + \mathcal{O}(r_{i+1}^4).$$

- Invert these series to determine the central pressure and density, $\{p_{i+1}, \epsilon_{i+1}\}$, in terms of the known quantities, $m_{i+1}, r_{i+1}, p_i, \epsilon_i$.



Can the Standard Solution to SSP⁻¹ be Improved?

- Standard solution to the relativistic SSP⁻¹ finds the equation of state, $\epsilon = \epsilon(\rho)$, represented as a table, $\{\rho_i, \epsilon_i\}$ for $i = 1, \dots, N$, and an interpolation formula.
- Standard solution has several weaknesses:
 - Solution converges (slowly) with the number of points, as N^{-p} .
 - Each new equation of state point, $\{\rho_i, \epsilon_i\}$, requires the knowledge of a separate new M-R curve point, $\{R_i, M_i\}$.
 - Accurate M-R curve points $\{R_i, M_i\}$ for neutron stars are scarce.

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- Spectral numerical methods typically converge more rapidly, and represent functions more efficiently than finite difference methods.
- Can spectral methods provide better (*i.e.* more practical and more accurate) solutions to the SSP^{-1} ?
- Can spectral methods provide interesting solutions to SSP^{-1} when only a few (*e.g.* two or three) M-R data points are available?

Outline for Solving SSP^{-1} Using Spectral Methods

- Assume the equation of state can be written in the form $\epsilon = \epsilon(\rho, \gamma_k)$, where the γ_k are a set of parameters.

For example, the equation of state could be written as a spectral expansion, $\epsilon = \epsilon(\rho, \gamma_k) = \sum_k \gamma_k \Phi_k(\rho)$, where the $\Phi_k(\rho)$ are spectral basis functions, e.g. $\Phi_k(\rho) = e^{ik\rho}$, or $\Phi_k(\rho) = P_k(\rho)$.

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- For a given equation of state, i.e. a particular choice of γ_k , solve the SSP to obtain a model M-R curve: $\{R(\rho_c, \gamma_k), M(\rho_c, \gamma_k)\}$.

Outline for Solving SSP⁻¹ Using Spectral Methods

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- Given a set of points from the “real” M-R curve, $\{R_i, M_i\}$, choose the parameters γ_k and \mathbf{p}_C^i that minimize the difference measure:

$$\chi^2 = \frac{1}{N_{\text{stars}}} \sum_{i=1}^{N_{\text{stars}}} \left\{ \left[\log \left(\frac{R(\mathbf{p}_C^i, \gamma_k)}{R_i} \right) \right]^2 + \left[\log \left(\frac{M(\mathbf{p}_C^i, \gamma_k)}{M_i} \right) \right]^2 \right\}$$

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- Resulting γ_k for $k = 1, \dots, N_{\gamma_k}$ determines an equation of state, $\epsilon = \epsilon(\mathbf{p}, \gamma_k)$, that provides an approximate solution of SSP^{-1} .

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- Can the spectral parameters γ_k be determined accurately and robustly by matching model masses and radii $\{R(p_C^i, \gamma_k), M(p_C^i, \gamma_k)\}$ to given $\{R_i, M_i\}$ data?
- These questions are best answered using a somewhat different form of the standard stellar structure problem (SSP).
- Digress (briefly) now to describe this alternate formulation that provides a more efficient and more accurate way to solve the SSP.

Alternative Representations of the SSP

- The standard Oppenheimer-Volkoff (OV) representation of the SSP equations determines $m(r)$ and $p(r)$, given an equation of state of the form $\epsilon = \epsilon(p)$.
- The outer boundary of the star is the point where $p(R) = 0$. This condition is difficult to solve numerically because the pressure goes to zero non-linearly there: $p \propto (R - r)^{\Gamma_0/(\Gamma_0 - 1)}$.

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- This problem can be simplified by introducing the relativistic enthalpy $h(p) = \int_0^p dp' / [\epsilon(p') + p']$, and re-writing the OV equations in terms of it:

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- The surface of the star is now the point where $h(R) = 0$. This condition is easier to solve numerically because the enthalpy goes to zero linearly there: $h(r) \propto (R - r)$.

Alternative Representations of the SSP II

- Simplify again by swapping the roles of h and r :

$$\frac{dm}{dh} = -\frac{4\pi\epsilon(h)r^3(r-2m)}{m+4\pi r^3\rho(h)}, \quad \frac{dr}{dh} = -\frac{r(r-2m)}{m+4\pi r^3\rho(h)}.$$

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- This form of the equations is easier to solve numerically:
 - The domain on which the solution $\{r(h), m(h)\}$ is defined, $h_c \geq h \geq 0$, is known *a priori*.
 - The total mass M and radius R are determined simply by evaluating the solution at $h = 0$, $\{R, M\} = \{r(0), m(0)\}$.

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- These alternative OV equations require that the equation of state, $\epsilon = \epsilon(p)$, be re-written as $\epsilon = \epsilon(h)$ and $p = p(h)$:
 - Start with the standard, $\epsilon = \epsilon(p)$.
 - Compute, $h(p) = \int_0^p dp' / [\epsilon(p') + p']$.
 - Invert to give $p = p(h)$.
 - Compose $\epsilon = \epsilon(p)$ with $p = p(h)$, to give $\epsilon = \epsilon(h) = \epsilon[p(h)]$.

Faithful Spectral Expansions of the Equation of State

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- Faithful here means *i)* that every choice of spectral parameters, α_k and β_k , corresponds to a possible physical equation of state, and *ii)* that every equation of state can be represented by such an expansion.

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- Faithful here means *i)* that every choice of spectral parameters, α_k and β_k , corresponds to a possible physical equation of state, and *ii)* that every equation of state can be represented by such an expansion.
- Faithful spectral expansions of the adiabatic index Γ do exist:

$$\Gamma(h) = \frac{\epsilon + p}{p} \frac{dp}{d\epsilon} = \exp \left[\sum_k \gamma_k \Phi_k(h) \right].$$

Faithful Spectral Expansions of the Equation of State II

- Every equation of state is determined by the adiabatic index $\Gamma(h)$:

$$\frac{d\epsilon}{dh} = \frac{(\epsilon + p)^2}{p\Gamma(h)}, \quad \frac{dp}{dh} = \epsilon + p.$$

- The solutions to these equations can be reduced to quadratures:

$$\begin{aligned} p(h) &= p_0 \exp \left[\int_{h_0}^h \frac{e^{h'}}{\mu(h')} dh' \right], \\ \epsilon(h) &= p(h) \frac{e^h - \mu(h)}{\mu(h)}, \\ \mu(h) &= \frac{p_0 e^{h_0}}{\epsilon_0 + p_0} + \int_{h_0}^h \frac{\Gamma(h') - 1}{\Gamma(h')} e^{h'} dh'. \end{aligned}$$

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$$\epsilon(h) = p(h) \frac{e^h - \mu(h)}{\mu(h)},$$

$$\mu(h) = \frac{p_0 e^{h_0}}{\epsilon_0 + p_0} + \int_{h_0}^h \frac{\Gamma(h') - 1}{\Gamma(h')} e^{h'} dh'.$$

- Choosing, $\log \Gamma(h) = \sum_k \gamma_k \Phi_k(h)$, for any spectral basis functions, $\Phi_k(h)$, results in a faithful parametrized equation of state of the desired form: $\epsilon = \epsilon(h, \gamma_k)$ and $p = p(h, \gamma_k)$.

Fitting Model Neutron-Star Equations of State

- How accurately and efficiently are realistic neutron-star equations of state represented by $\epsilon = \epsilon(h, \gamma_k)$ and $p = p(h, \gamma_k)$, when $\Gamma(h)$ is given by

$$\Gamma(h) = \exp \left\{ \sum_{k=0}^{N_{\gamma_k}-1} \gamma_k \left[\log \left(\frac{h}{h_0} \right) \right]^k \right\} ?$$

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- Let $\{p_i, \epsilon_i, h_i\}$, for $i = 1, \dots, N_{\text{EOS}}$ denote one of the standard tabulated realistic neutron-star equations of state.
- Find the spectral parameters γ_k that minimize the fitting error:

$$\left(\Delta_{N_{\gamma_k}}^{\text{EOS}} \right)^2 = \frac{1}{N_{\text{EOS}}} \sum_{i=1}^{N_{\text{EOS}}} \left[\log \left(\frac{\epsilon(h_i, \gamma_k)}{\epsilon_i} \right) \right]^2 .$$

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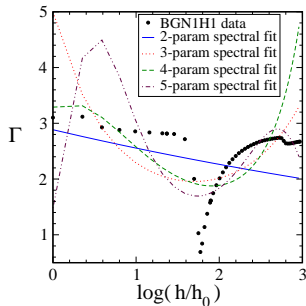
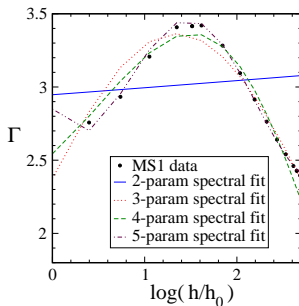
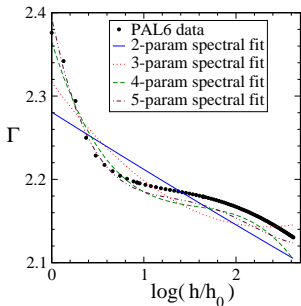
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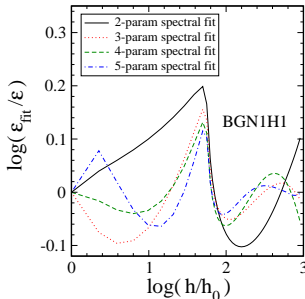
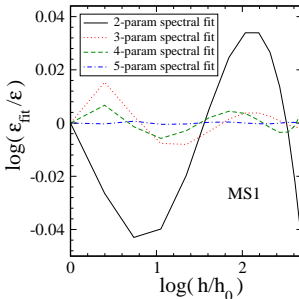
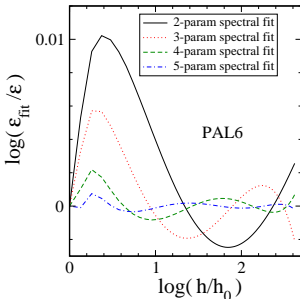
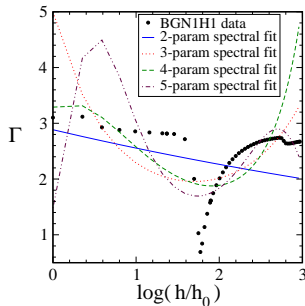
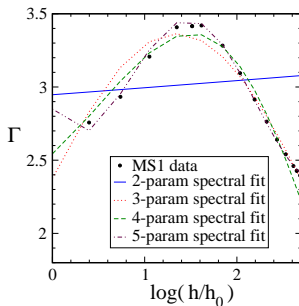
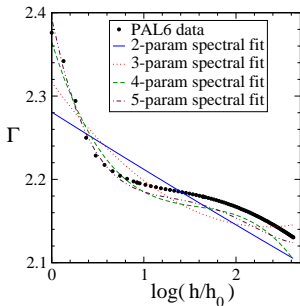
- The average values of these fitting errors, $\Delta_{N_{\gamma_k}}^{\text{EOS}}$, for 34 realistic neutron-star equations of state are:

$$\begin{aligned} \Delta_2^{\text{EOS}} &= 0.032, & \Delta_3^{\text{EOS}} &= 0.017, \\ \Delta_4^{\text{EOS}} &= 0.012, & \Delta_5^{\text{EOS}} &= 0.0089. \end{aligned}$$

Spectral Fits of Model Neutron-Star Equations of State



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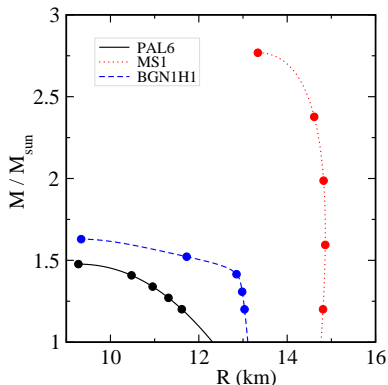


Spectral Solution of SSP^{-1}

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Spectral Solution of SSP^{-1}

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- Choose mock data points $\{R_i, M_i\}$ for neutron-star models computed with 34 realistic equations of state.



Spectral Solution of SSP⁻¹ II

- Fix the spectral expansion coefficients γ_k by minimizing,

$$\chi^2 = \frac{1}{N_{\text{stars}}} \sum_{i=1}^{N_{\text{stars}}} \left\{ \left[\log \left(\frac{M(h_c^i, \gamma_k)}{M_i} \right) \right]^2 + \left[\log \left(\frac{R(h_c^i, \gamma_k)}{R_i} \right) \right]^2 \right\}.$$

with respect to variations in γ_k , and variations in the central values of the enthalpy for each star, h_c^i .

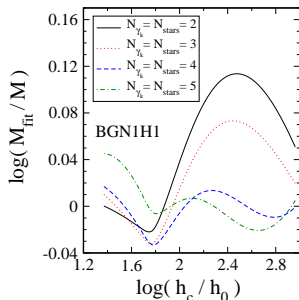
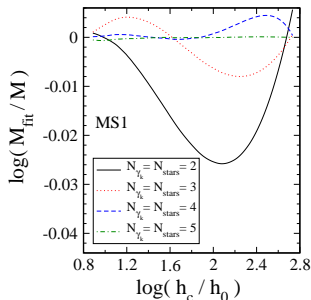
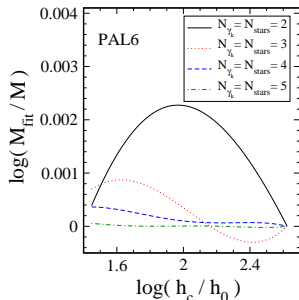
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with respect to variations in γ_k , and variations in the central values of the enthalpy for each star, h_c^i .

- Compare the resulting M-R curve $\{R(h_c, \gamma_k), M(h_c, \gamma_k)\}$ with the exact curve from the known equation of state $\{R(h_c), M(h_c)\}$.



Spectral Solutions to SSP⁻¹ III

- Next evaluate the equation of state fitting errors, $\Delta_{N_{\gamma k}}^{MR}$,

$$\left(\Delta_{N_{\gamma k}}^{MR}\right)^2 = \frac{1}{N_{\text{EOS}}} \sum_{i=1}^{N_{\text{EOS}}} \left[\log \left(\frac{\epsilon(h_i, \gamma_k)}{\epsilon_i} \right) \right]^2$$

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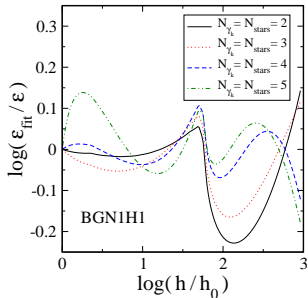
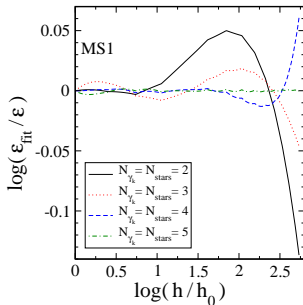
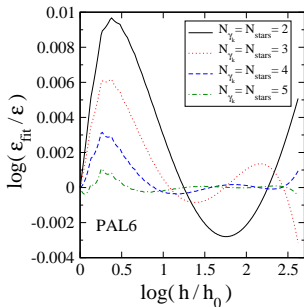
- The average values of $\Delta_{N_{\gamma k}}^{MR}$ (with $N_{\gamma k} = N_{\text{stars}}$) determined in this way for 34 realistic model equations of state are:

$$\begin{array}{ll} \Delta_2^{MR} = 0.040, & \Delta_2^{EOS} = 0.032, \\ \Delta_3^{MR} = 0.029, & \Delta_3^{EOS} = 0.017, \\ \Delta_4^{MR} = 0.023, & \Delta_4^{EOS} = 0.012, \\ \Delta_5^{MR} = 0.017, & \Delta_5^{EOS} = 0.0089. \end{array}$$

- The accuracy of these solutions to the SSP⁻¹ is quite impressive, even though the number of M-R data used is very small.

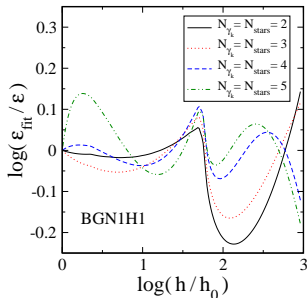
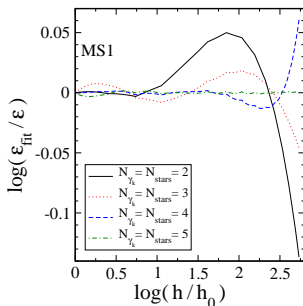
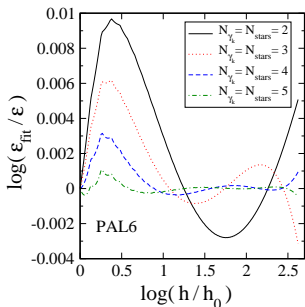
Spectral Solutions to SSP⁻¹ IV

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Spectral Solutions to SSP⁻¹ IV

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- The convergence of $\Delta_{N_{\gamma_k}}^{MR}$ is not as good as $\Delta_{N_{\gamma_k}}^{EOS}$. Perhaps our χ^2 minimization finds local not global minima?

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$$\frac{dm}{dh} = \mathcal{M}(m, r, h), \quad \frac{dr}{dh} = \mathcal{R}(m, r, h), \quad \frac{d\lambda}{dh} = \mathcal{L}(\lambda, m, r, h),$$

with macroscopic observables: $M = m(0)$, $R = r(0)$ and $\Lambda = \lambda(0)$.

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- Compare average accuracy of the resulting equations of state $\Delta_N^{M\Lambda}$ with those obtained using mass-radius data, Δ_N^{MR} .
(Warning: Preliminary results, hot-off-the-press.)

$$\Delta_2^{M\Lambda} = 0.040, \quad \Delta_3^{M\Lambda} = 0.029, \quad \Delta_4^{M\Lambda} = 0.023, \quad \Delta_5^{M\Lambda} = 0.018.$$

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- Gravitational wave measurements of neutron star masses M_i and tidal deformabilities Λ_i can be used to determine the neutron star equation of state with about the same level of accuracy as that obtainable with more traditional mass M_i radius R_i data.